# Workshop in honor of Jean-Paul Laumond (July 11, 2022)

#### Speakers:

Stéphane Mallat (Collège de France)

Alin Albu-Schäffer (TUM)

Daniel Andler (Sorbonne Université et ENS-PSL)

Antonio Bicchi (Pisa)

John Canny (UC Berkeley)

Justin Carpentier (Inria)

Alessandro De Luca (Sapienza)

Ken Goldberg (UC Berkeley)

Vincent Hayward (Sorbonne Université)

Matt Mason (CMU)

Katja Mombaur (Waterloo)

Céline Pieters (Vienna)

Jean Ponce (Inria)

Philippe Souères (LAAS-CNRS)

Eiichi Yoshida (Tokyo University of Science)

Session chairs:

Martial Hebert (Carnegie-Mellon University)

Steven Lavalle (University of Oulu)

Nicolas Mansard (LAAS/CNRS)

Nicolas Siméon

### Program:

8h30 - 9h00 Breakfast

## 9h00 - 9h15 Welcome and opening remarks

Stéphane Mallat

# 9h15 – 10h55 **Session 1** chaired by Nicolas Siméon

- Philippe Souères The adventure of optimal paths for nonholonomic wheeled robots
- Matt Mason How should a wheelchair think about distance? In memory of Jean-Paul Laumond
- Alin Albu-Schäffer A geometric perspective to robot nonlinear oscillations with application to locomotion
- John Canny Explainable and advisable self-driving vehicle models

## 10h55 - 11h25 Break

### 11h25 - 12h40 Session 2 chaired by Nicolas Mansard

- Elichi Yoshida Human and humanoid together looking back our scientific adventure and into future
- Katja Mombaur From optimality principles in human movement to motion intelligence in human-centred robots
- Justin Carpentier Robotics: computational foundations of artificial motion

#### 12h40 – 14h20 **Lunch** (everyone on their own)

#### 14h20 – 16h00 **Session 3** chaired by Martial Hebert

- Céline Pieters Talking about moving machines: language and representations
- Ken Goldberg Art and robots: a tribute to Jean-Paul Laumond
- Daniel Andler Is having a body a sufficient and / or necessary condition for an AI system to attain intelligence?
- Antonio Bicchi Of bots and men

### 16h00 - 16h30 Break

### 16h30 – 17h45 **Session 4** chaired by Steve Lavalle

- Vincent Hayward Tactile mechanics and its impact on the messages sent to the brain
- Alessandro de Luca On the control of physical human-robot interaction
- Jean Ponce A swept-volume metric structure for configuration space

# 17h45 – 18h00 Closing remarks